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Fig. 2.44 Mechanical system for Problem 2.2 Solution: The key is to draw the Free Body Diagram (FBD) in order to keep the signs right.

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functions, one can begin to analyze the stability of feedback systems using loop analysis, which allows us to reason about the closed loop behavior (stability) of a system from its open loop characteristics. This is the subject of Chapter 9, which revolves around the Nyquist stability criterion.

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expansion, complex conjugate poles have coefficients that are also complex conjugates. (The result of this relationship is that whenever complex conjugate pairs of poles are present, only one of the coefficients needs to be computed.)

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